


# More on Constrained Optimisation

**Yingzhen Li**

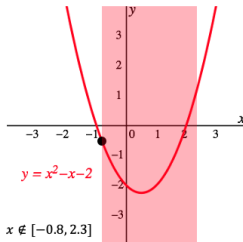
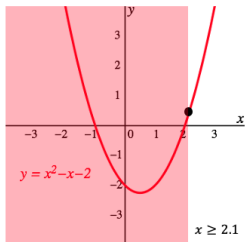
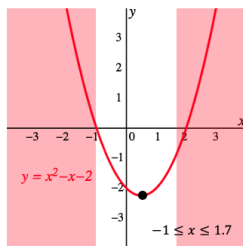
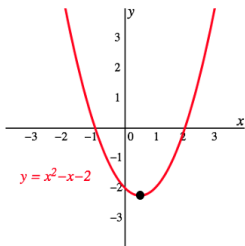
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# From unconstrained to constrained optimisation

Find minimum for function  $f(x) = x^2 - x - 2$ :



# Constrained optimisation: Set-up

A constrained optimisation problem typically has the following form:

$$\min_{\mathbf{x}} L(\mathbf{x})$$

subject to  $g_i(\mathbf{x}) \leq 0, i = 1, \dots, N$  (inequality constraints)

$h_j(\mathbf{x}) = 0, j = 1, \dots, M$  (equality constraints)

Strategies to solve a constrained problem:

- ▶ reparameterise  $\mathbf{x}$  to directly satisfy the constraints
- ▶ **Last lecture**: the Lagrange multiplier method

# Constrained optimisation: Set-up

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Strategies to solve a constrained problem:

- ▶ reparameterise  $\mathbf{x}$  to directly satisfy the constraints
- ▶ **Last lecture**: the Lagrange multiplier method
- ▶ **This lecture**: the Karush-Kuhn-Tucker (KKT) conditions

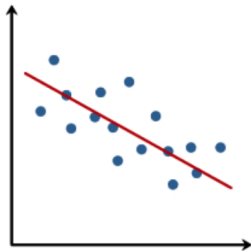
# Example: Constrained linear regression

Fitting **constrained** linear regression:

- ▶ Dataset:  $\mathcal{D} = \{\mathbf{X}, \mathbf{y}\}$ ,  
 $\mathbf{X} = [\mathbf{x}_1, \dots, \mathbf{x}_N]^\top \in \mathbb{R}^{N \times D}$ ,  
 $\mathbf{y} = [y_1, \dots, y_N]^\top \in \mathbb{R}^{N \times 1}$
- ▶ Goal: find  $\boldsymbol{\theta} \in \mathbb{R}^{D \times 1}$  such that

$$\mathbf{y} \approx \mathbf{X}\boldsymbol{\theta}$$

$$\|\boldsymbol{\theta}\|_2^2 \leq \delta, \quad \delta > 0$$



## Example: Constrained linear regression

A typical **constrained** linear regression model:

- ▶  $\mathbf{x} \in \mathbb{R}^{D \times 1}$ : input features;  $y \in \mathbb{R}$ : output value
- ▶ Model:

$$f(\mathbf{x}, \boldsymbol{\theta}) = \mathbf{x}^\top \boldsymbol{\theta}, \quad y = f(\mathbf{x}, \boldsymbol{\theta}) + \epsilon, \quad \epsilon \sim \mathcal{N}(0, \sigma^2)$$

- ▶ The **constrained optimisation** problem:

$$\min_{\boldsymbol{\theta}} L(\boldsymbol{\theta}) = \frac{1}{2\sigma^2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|_2^2$$

$$\text{subject to} \quad \|\boldsymbol{\theta}\|_2^2 - \delta \leq 0$$

## Example: Constrained linear regression

Solution with Lagrange multiplier method:

Write down an alternative objective called **Lagrangian**:

$$L(\boldsymbol{\theta}; \lambda) = \frac{1}{2\sigma^2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|_2^2 + \lambda (\|\boldsymbol{\theta}\|_2^2 - \delta)$$

- ▶ We will find minimum of  $L(\boldsymbol{\theta}; \lambda)$  w.r.t.  $\boldsymbol{\theta}$ 
  - ▶ as part of the KKT conditions

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- ▶ We will find minimum of  $L(\boldsymbol{\theta}; \lambda)$  w.r.t.  $\boldsymbol{\theta}$ 
  - ▶ as part of the KKT conditions
- ▶ We require the Lagrange multiplier  $\lambda \geq 0$ 
  - ▶ this encourages minimiser of  $L(\boldsymbol{\theta}; \lambda)$  to satisfy the constraint
  - ▶ as part of the KKT conditions
- ▶ We will solve  $\lambda$  using other parts of the KKT conditions



## Example: Constrained linear regression

Solution with Lagrange multiplier method:

$$L(\boldsymbol{\theta}; \lambda) = \frac{1}{2\sigma^2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|_2^2 + \lambda (\|\boldsymbol{\theta}\|_2^2 - \delta)$$

Find minimum of  $L(\boldsymbol{\theta}; \lambda)$  w.r.t.  $\boldsymbol{\theta}$  by setting  $\nabla_{\boldsymbol{\theta}} L(\boldsymbol{\theta}; \lambda) = 0$ :

$$\nabla_{\boldsymbol{\theta}} L(\boldsymbol{\theta}; \lambda) = -\frac{1}{\sigma^2} \mathbf{X}^\top (\mathbf{y} - \mathbf{X}\boldsymbol{\theta}) + 2\lambda \boldsymbol{\theta} = 0$$

**KKT stationarity condition:**  $\nabla_{\boldsymbol{\theta}} L(\boldsymbol{\theta}; \lambda) = 0$

$$\Rightarrow \boldsymbol{\theta}^*(\lambda) = (\sigma^2 \lambda' \mathbf{I} + \mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y}, \quad \lambda' = 2\lambda$$

## Example: Constrained linear regression

Solution with Lagrange multiplier method:

$$L(\boldsymbol{\theta}; \lambda) = \frac{1}{2\sigma^2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|_2^2 + \lambda (\|\boldsymbol{\theta}\|_2^2 - \delta)$$

Find  $\lambda$  to substitute in  $\boldsymbol{\theta}^*(\lambda) = (2\sigma^2\lambda\mathbf{I} + \mathbf{X}^\top\mathbf{X})^{-1}\mathbf{X}^\top\mathbf{y}$ :

This is done by solving the remaining KKT conditions:

- ▶ **primal feasibility:**  $\|\boldsymbol{\theta}^*(\lambda)\|_2^2 - \delta \leq 0$

## Example: Constrained linear regression

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This is done by solving the remaining KKT conditions:

- ▶ **primal feasibility:**  $\|\boldsymbol{\theta}^*(\lambda)\|_2^2 - \delta \leq 0$
- ▶ **dual feasibility:**  $\lambda \geq 0$
- ▶ **complementary slackness:**  $\lambda(\|\boldsymbol{\theta}^*(\lambda)\|_2^2 - \delta) = 0$

## Example: Constrained linear regression

$$L(\boldsymbol{\theta}; \lambda) = \underbrace{\frac{1}{2\sigma^2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|_2^2}_{=L(\boldsymbol{\theta})} + \lambda(\|\boldsymbol{\theta}\|_2^2 - \delta)$$

**dual feasibility:**  $\lambda \geq 0$

▸ for any  $\boldsymbol{\theta}$  s.t.  $\|\boldsymbol{\theta}\|_2^2 \leq \delta$

$$\lambda(\|\boldsymbol{\theta}\|_2^2 - \delta) \leq 0 \Rightarrow L(\boldsymbol{\theta}) \geq L(\boldsymbol{\theta}; \lambda)$$

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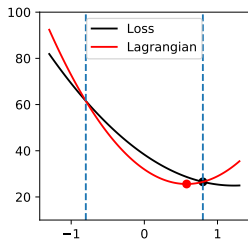
- ▶ for any  $\boldsymbol{\theta}$  s.t.  $\|\boldsymbol{\theta}\|_2^2 \leq \delta$

$$\lambda(\|\boldsymbol{\theta}\|_2^2 - \delta) \leq 0 \Rightarrow L(\boldsymbol{\theta}) \geq L(\boldsymbol{\theta}; \lambda)$$

- ▶ Assume  $\boldsymbol{\theta}_\delta^* = \arg \min_{\|\boldsymbol{\theta}\|_2^2 \leq \delta} L(\boldsymbol{\theta})$ ,

then for a fixed  $\lambda \geq 0$

$$\min_{\|\boldsymbol{\theta}\|_2^2 \leq \delta} L(\boldsymbol{\theta}) := L(\boldsymbol{\theta}_\delta^*) \geq L(\boldsymbol{\theta}_\delta^*; \lambda) \geq \min_{\|\boldsymbol{\theta}\|_2^2 \leq \delta} L(\boldsymbol{\theta}; \lambda)$$



**We want a tight lower-bound!**

## Example: Constrained linear regression

$$L(\boldsymbol{\theta}; \lambda) = \underbrace{\frac{1}{2\sigma^2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|_2^2}_{=L(\boldsymbol{\theta})} + \lambda(\|\boldsymbol{\theta}\|_2^2 - \delta)$$

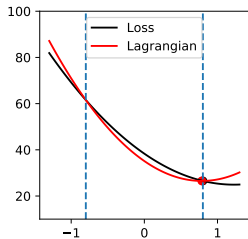
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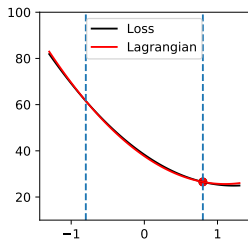
- ▶ for any  $\boldsymbol{\theta}$  s.t.  $\|\boldsymbol{\theta}\|_2^2 \leq \delta$

$$\lambda(\|\boldsymbol{\theta}\|_2^2 - \delta) \leq 0 \Rightarrow L(\boldsymbol{\theta}) \geq L(\boldsymbol{\theta}; \lambda)$$

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**complementary slackness:**  $\lambda(\|\boldsymbol{\theta}^*(\lambda)\|_2^2 - \delta) = 0$

- ▶ For  $\lambda^* \geq 0$  satisfying complementary slackness, this makes the lower-bound tight:

$$\min_{\|\boldsymbol{\theta}\|_2^2 \leq \delta} L(\boldsymbol{\theta}; \lambda^*) = L(\boldsymbol{\theta}^*(\lambda^*); \lambda^*) = L(\boldsymbol{\theta}^*(\lambda^*)) \leq \min_{\|\boldsymbol{\theta}\|_2^2 \leq \delta} L(\boldsymbol{\theta})$$

$$\Rightarrow \arg \min_{\|\boldsymbol{\theta}\|_2^2 \leq \delta} L(\boldsymbol{\theta}) = \boldsymbol{\theta}^*(\lambda^*)$$

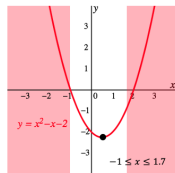


## Example: Constrained linear regression

$$L(\boldsymbol{\theta}; \lambda) = \underbrace{\frac{1}{2\sigma^2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|_2^2}_{=L(\boldsymbol{\theta})} + \lambda(\|\boldsymbol{\theta}\|_2^2 - \delta)$$

**complementary slackness:**  $\lambda(\|\boldsymbol{\theta}^*(\lambda)\|_2^2 - \delta) = 0$

- ▶ Case 1:  $\lambda^* = 0$ 
  - ▶ check **primal feasibility:**  $\|\boldsymbol{\theta}^*(0)\|_2^2 - \delta \leq 0$ ?
  - ▶ if so, then  $\arg \min_{\|\boldsymbol{\theta}\|_2^2 \leq \delta} L(\boldsymbol{\theta}) = \boldsymbol{\theta}^*(0)$
  - ▶ in this case we call the constraint **redundant**

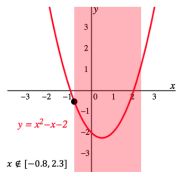


## Example: Constrained linear regression

$$L(\boldsymbol{\theta}; \lambda) = \underbrace{\frac{1}{2\sigma^2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|_2^2}_{=L(\boldsymbol{\theta})} + \lambda(\|\boldsymbol{\theta}\|_2^2 - \delta)$$

**complementary slackness:**  $\lambda(\|\boldsymbol{\theta}^*(\lambda)\|_2^2 - \delta) = 0$

- ▶ Case 2:  $\lambda^* > 0$ ,  $\|\boldsymbol{\theta}^*(\lambda^*)\|_2^2 = \delta$ 
  - ▶ this happens when  $\|\boldsymbol{\theta}^*(0)\|_2^2 - \delta > 0$
  - ▶  $\arg \min_{\|\boldsymbol{\theta}\|_2^2 \leq \delta} L(\boldsymbol{\theta}) = \boldsymbol{\theta}^*(\lambda^*)$
  - ▶ in this case we say the constraint is **binding**

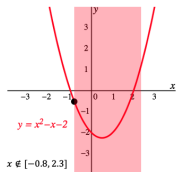


## Example: Constrained linear regression

$$L(\boldsymbol{\theta}; \lambda) = \underbrace{\frac{1}{2\sigma^2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|_2^2}_{=L(\boldsymbol{\theta})} + \lambda(\|\boldsymbol{\theta}\|_2^2 - \delta)$$

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One-to-one relationship between  $\lambda^*$  and  $\delta$   
by solving  $\|\boldsymbol{\theta}^*(\lambda)\|_2^2 = \delta$  for  $\lambda$

## Connections with ridge regression

Constrained linear regression:

$$\min_{\boldsymbol{\theta}} \frac{1}{2\sigma^2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|_2^2$$

subject to  $\|\boldsymbol{\theta}\|_2^2 - \delta \leq 0$

Lagrangian:

$$L(\boldsymbol{\theta}; \lambda) = \frac{1}{2\sigma^2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|_2^2 + \lambda (\|\boldsymbol{\theta}\|_2^2 - \delta)$$

Ridge regression: for a given  $\lambda \geq 0$

$$\min_{\boldsymbol{\theta}} \frac{1}{2\sigma^2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|_2^2 + \lambda \|\boldsymbol{\theta}\|_2^2$$

One-to-one relationship: when choosing  $\lambda \geq 0$  for ridge regression, this is also implicitly choosing  $\delta$  so that  $\|\boldsymbol{\theta}^*(\lambda)\|_2^2 = \delta$

## A summary of the KKT conditions

$$\begin{aligned} & \min_{\mathbf{x}} L(\mathbf{x}) \\ \text{subject to} & \quad g_i(\mathbf{x}) \leq 0, \quad i = 1, \dots, N \\ & \quad h_j(\mathbf{x}) = 0, \quad j = 1, \dots, M \end{aligned}$$

Lagrangian:

$$L(\mathbf{x}; \{\lambda_i\}, \{v_j\}) = L(\mathbf{x}) + \sum_{i=1}^N \lambda_i g_i(\mathbf{x}) + \sum_{j=1}^M v_j h_j(\mathbf{x})$$

KKT conditions for the solutions of  $\mathbf{x}, \{\lambda_i\}, \{v_j\}$ :

- ▶ **stationarity:**  $\nabla_{\mathbf{x}} L(\mathbf{x}; \{\lambda_i\}, \{v_j\}) = 0$
- ▶ **primal feasibility:**  $g_i(\mathbf{x}) \leq 0, h_j(\mathbf{x}) = 0$  for all  $i, j$
- ▶ **dual feasibility:**  $\lambda_i \geq 0$  for all  $i$
- ▶ **complementary slackness:**  $\lambda_i g_i(\mathbf{x}) = 0$  for all  $i$

# A summary of the KKT conditions

A constrained optimisation problem with equality constraints:

$$\min_{\mathbf{x}} L(\mathbf{x})$$

subject to  $h_j(\mathbf{x}) = 0, j = 1, \dots, M$  (equality constraints)

Lagrangian:

$$L(\mathbf{x}; \{v_j\}) = L(\mathbf{x}) + \sum_{j=1}^M v_j h_j(\mathbf{x})$$

KKT conditions for the solutions of  $x, \{v_j\}$ :

- ▶ **stationarity:**  $\nabla_{\mathbf{x}} L(\mathbf{x}; \{v_j\}) = 0$
- ▶ **primal feasibility:**  $h_j(\mathbf{x}) = 0$  for all  $j$

Dual feasibility & complementary slackness conditions not applicable

(break)

# Dual optimisation

The primal problem

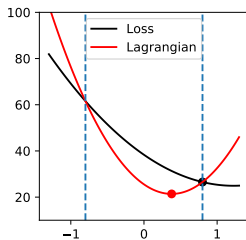
$$\begin{aligned} \min_{\mathbf{x}} L(\mathbf{x}) \\ \text{subject to } g(\mathbf{x}) \leq 0 \end{aligned}$$

Lagrangian:  $L(\mathbf{x}; \lambda) = L(\mathbf{x}) + \lambda g(\mathbf{x})$

**dual feasibility:**  $\lambda \geq 0$

▸ for  $\mathbf{x}$  satisfying **primal feasibility:**

$$\lambda g(\mathbf{x}) \leq 0, \forall \lambda \geq 0 \quad \Rightarrow \quad L(\mathbf{x}) \geq L(\mathbf{x}; \lambda)$$





# Dual optimisation

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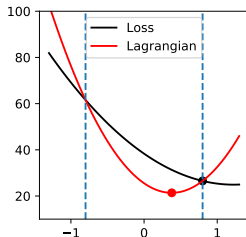
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$$\lambda g(\mathbf{x}) \leq 0, \forall \lambda \geq 0 \quad \Rightarrow \quad L(\mathbf{x}) \geq L(\mathbf{x}; \lambda)$$

$$\min_{g(\mathbf{x}) \leq 0} L(\mathbf{x}) := L(\mathbf{x}^*) \geq L(\mathbf{x}^*; \lambda) \geq \min_{g(\mathbf{x}) \leq 0} L(\mathbf{x}; \lambda) \geq \underbrace{\min_x L(\mathbf{x}; \lambda)}_{:= L(\mathbf{x}^*(\lambda); \lambda)}$$



# Dual optimisation

The primal problem

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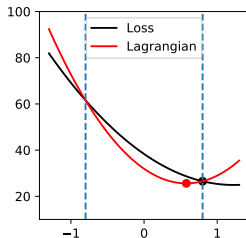
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▶ for  $\mathbf{x}$  satisfying **primal feasibility**:

$$\lambda g(\mathbf{x}) \leq 0, \forall \lambda \geq 0 \quad \Rightarrow \quad L(\mathbf{x}) \geq L(\mathbf{x}; \lambda)$$

$$\min_{g(\mathbf{x}) \leq 0} L(\mathbf{x}) := L(\mathbf{x}^*) \geq L(\mathbf{x}^*; \lambda) \geq \min_{g(\mathbf{x}) \leq 0} L(\mathbf{x}; \lambda) \geq \underbrace{\min_{\mathbf{x}} L(\mathbf{x}; \lambda)}_{:= L(\mathbf{x}^*(\lambda); \lambda)}$$

Let's define  $D(\lambda) = \min_{\mathbf{x}} L(\mathbf{x}; \lambda) = L(\mathbf{x}^*(\lambda); \lambda)$



# Dual optimisation

The primal problem

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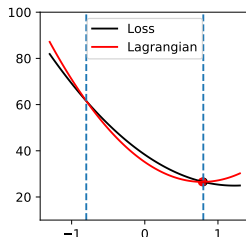
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**dual feasibility:**  $\lambda \geq 0$

▸ for  $\mathbf{x}$  satisfying **primal feasibility**:

$$\lambda g(\mathbf{x}) \leq 0, \forall \lambda \geq 0 \quad \Rightarrow \quad L(\mathbf{x}) \geq L(\mathbf{x}; \lambda)$$

$$\min_{g(\mathbf{x}) \leq 0} L(\mathbf{x}) := L(\mathbf{x}^*) \geq L(\mathbf{x}^*; \lambda) \geq D(\lambda) := L(\mathbf{x}^*(\lambda); \lambda)$$



The inequalities are true for any  $\lambda \geq 0$

# Dual optimisation

The primal problem

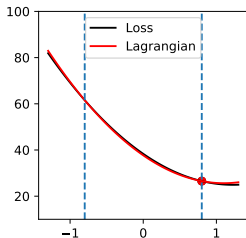
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# Dual optimisation

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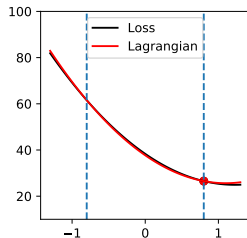
**dual feasibility:**  $\lambda \geq 0$

▸ if  $\exists \lambda^* > 0$  s.t. **complementary slackness:**

$$\lambda^* g(\mathbf{x}^*(\lambda^*)) = 0$$

$$\Rightarrow L(\mathbf{x}^*(\lambda^*)) = L(\mathbf{x}^*(\lambda^*); \lambda^*)$$

$$\min_{g(\mathbf{x}) \leq 0} L(\mathbf{x}) := L(\mathbf{x}^*) \geq L(\mathbf{x}^*; \lambda^*) \geq \underbrace{D(\lambda^*)}_{\lambda^* := \arg \max_{\lambda \geq 0} D(\lambda)}$$



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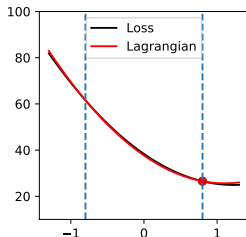
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$$\Rightarrow L(\mathbf{x}^*(\lambda^*)) = L(\mathbf{x}^*(\lambda^*); \lambda^*)$$

$$\min_{g(\mathbf{x}) \leq 0} L(\mathbf{x}) \geq \max_{\lambda \geq 0} D(\lambda) \geq D(\lambda^*) = L(\mathbf{x}^*(\lambda^*); \lambda^*) = L(\mathbf{x}^*(\lambda^*))$$



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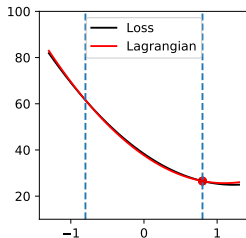
▸ if  $\exists \lambda^* > 0$  s.t. **complementary slackness:**

$$\lambda^* g(\mathbf{x}^*(\lambda^*)) = 0$$

$$\Rightarrow L(\mathbf{x}^*(\lambda^*)) = L(\mathbf{x}^*(\lambda^*); \lambda^*)$$

$$\min_{g(\mathbf{x}) \leq 0} L(\mathbf{x}) \geq \max_{\lambda \geq 0} D(\lambda) \geq D(\lambda^*) = L(\mathbf{x}^*(\lambda^*); \lambda^*) = L(\mathbf{x}^*(\lambda^*))$$

Notice  $g(\mathbf{x}^*(\lambda^*)) \leq 0 \quad \Rightarrow \quad \mathbf{x}^* = \mathbf{x}^*(\lambda^*)$



# Dual optimisation

The primal problem

$$\begin{aligned} \min_{\mathbf{x}} L(\mathbf{x}) \\ \text{subject to } g(\mathbf{x}) \leq 0 \end{aligned}$$

Lagrangian:  $L(\mathbf{x}; \lambda) = L(\mathbf{x}) + \lambda g(\mathbf{x})$

**dual feasibility:**  $\lambda \geq 0$

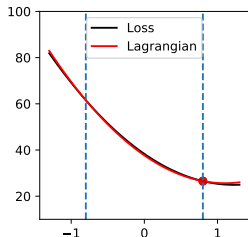
▶ if  $\exists \lambda^* > 0$  s.t. **complementary slackness:**

$$\lambda^* g(\mathbf{x}^*(\lambda^*)) = 0$$

$$\Rightarrow L(\mathbf{x}^*(\lambda^*)) = L(\mathbf{x}^*(\lambda^*); \lambda^*)$$

$$\min_{g(\mathbf{x}) \leq 0} L(\mathbf{x}) = \max_{\lambda \geq 0} D(\lambda) = D(\lambda^*)$$

Maximise  $D(\lambda)$  w.r.t.  $\lambda$  to find such  $\lambda^*$ !





# Primal & dual forms

Primal problem:

$$\begin{aligned} & \min_{\mathbf{x}} L(\mathbf{x}) \\ & \text{subject to } g(\mathbf{x}) \leq 0 \end{aligned}$$

Dual problem:

$$\begin{aligned} & \max_{\lambda} D(\lambda) := \min_{\mathbf{x}} (L(\mathbf{x}) + \lambda g(\mathbf{x})) \\ & \text{subject to } \lambda \geq 0 \end{aligned}$$

# Primal & dual forms

Primal problem:

$$\begin{aligned} \min_{\mathbf{x}} L(\mathbf{x}) \\ \text{subject to } g(\mathbf{x}) \leq 0 \end{aligned}$$

Dual problem:

$$\begin{aligned} \max_{\lambda} D(\lambda) := \min_{\mathbf{x}} (L(\mathbf{x}) + \lambda g(\mathbf{x})) \\ \text{subject to } \lambda \geq 0 \end{aligned}$$

Connected via the KKT conditions:

- ▶  $\mathbf{x}^*(\lambda)$  and  $D(\lambda) = L(\mathbf{x}^*(\lambda); \lambda)$  comes from stationarity
- ▶ **We assumed primal feasibility  $g(\mathbf{x}^*(\lambda^*)) \leq 0$**
- ▶  $\lambda \geq 0$  comes from dual feasibility
- ▶ **the max. dual problem comes from complementary slackness**

# Primal & dual forms

Primal problem:

$$\begin{aligned} \min_{\mathbf{x}} L(\mathbf{x}) \\ \text{subject to } g(\mathbf{x}) \leq 0 \end{aligned}$$

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- ▶ ~~We assumed primal feasibility  $g(\mathbf{x}^*(\lambda^*)) \leq 0$~~
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- ▶ **the max. dual problem comes from complementary slackness**

# Primal & dual forms

Primal problem:

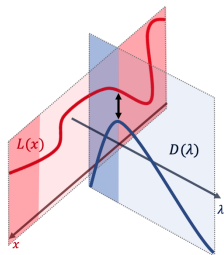
$$\begin{aligned} \min_{\mathbf{x}} L(\mathbf{x}) \\ \text{subject to } g(\mathbf{x}) \leq 0 \end{aligned}$$

Dual problem:

$$\begin{aligned} \max_{\lambda} D(\lambda) := \min_{\mathbf{x}} (L(\mathbf{x}) + \lambda g(\mathbf{x})) \\ \text{subject to } \lambda \geq 0 \end{aligned}$$

Weak duality (always hold):

$$\min_{g(\mathbf{x}) \leq 0} L(\mathbf{x}) \geq \max_{\lambda \geq 0} D(\lambda)$$



# Primal & dual forms

Primal problem:

$$\begin{aligned} \min L(\boldsymbol{\theta}) \\ \text{subject to } g(\boldsymbol{\theta}) \leq 0 \end{aligned}$$

Dual problem:

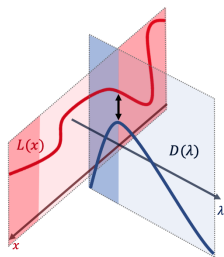
$$\begin{aligned} \max D(\lambda) := \min_{\boldsymbol{\theta}} (L(\boldsymbol{\theta}) + \lambda g(\boldsymbol{\theta})) \\ \text{subject to } \lambda \geq 0 \end{aligned}$$

Weak duality (always hold):

$$\min_{g(x) \leq 0} L(x) \geq \max_{\lambda \geq 0} D(\lambda)$$

Strong duality

$$\min_{g(\boldsymbol{\theta}) \leq 0} L(\boldsymbol{\theta}) = \max_{\lambda \geq 0} D(\lambda)$$



# Summary

- ▶ Constrained optimisation with equality & inequality constraints
  - ▶ The Lagrange multiplier method
  - ▶ KKT conditions
- ▶ Examples
  - ▶ PCA (equality constraints)
  - ▶ Linear regression with inequality constraints  
( $\ell_2$ -norm constraints, connections with ridge regression)
- ▶ Primal & dual forms
  - ▶ Primal minimisation problem with inequality constraints  
 $\Rightarrow$  dual maximisation problem with inequality constraints
  - ▶ Connections shown using KKT conditions
  - ▶ Duality gap: Dual problem might only return a lower-bound