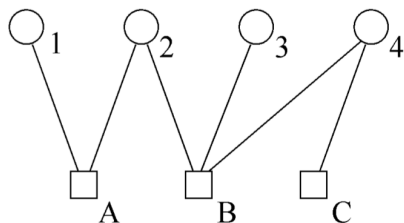


Outline

- ▶ Belief Propagation
- ▶ Bethe Method
- ▶ EP and Divergences

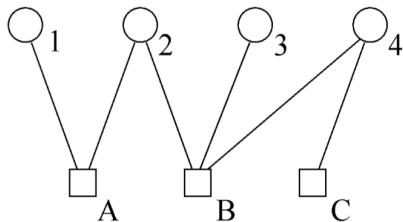
Factor Graph



$$p(x_1, x_2, x_3, x_4) = \frac{1}{Z} f_A(x_1, x_2) f_B(x_2, x_3, x_4) f_C(x_4) \quad (1)$$

$$p(\mathbf{x}_S) = \sum_{\mathbf{x} \setminus \mathbf{x}_S} p(\mathbf{x}), \quad \forall S \subset \{x_1, x_2, x_3, x_4\}$$

Message Passing



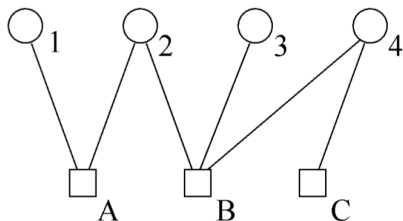
- ▶ message from factor to node:

$$M_{a \rightarrow i}(x_i) := \sum_{\mathbf{x}_a \setminus x_i} f_a(\mathbf{x}_a) \prod_{j \in N(a) \setminus i} M_{j \rightarrow a}(x_j)$$

- ▶ message from node to factor:

$$M_{j \rightarrow a}(x_j) := \prod_{a' \in N(j) \setminus a} M_{a' \rightarrow j}(x_j)$$

Message Passing



- ▶ belief (or pseudo prob.) of the node:

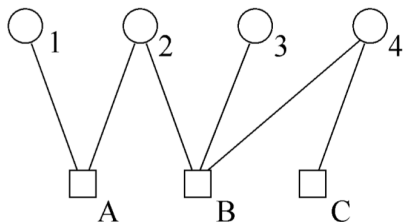
$$q_i(x_i) \propto \prod_{a \in N(i)} M_{a \rightarrow i}(x_i)$$

- ▶ belief of the factor:

$$q_a(\mathbf{x}_a) \propto f_a(\mathbf{x}_a) \prod_{i \in N(a)} M_{i \rightarrow a}(x_i)$$

- ▶ $q_i(x_i) = \sum_{\mathbf{x}_a \setminus x_i} q_a(\mathbf{x}_a)$

Why Loopy Belief Propagation



- ▶ $q_i(x_i) = p(x_i)$ if no loops in the graph
- ▶ The approximation by BP will be worse with more loops
- ▶ Loopy BP: region-based free energy approximations

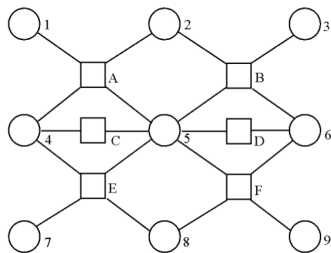
Free Energies

- ▶ Boltzmann's Law: $p(\mathbf{x}) = \frac{1}{Z} e^{-E(\mathbf{x})}$
 $E(\mathbf{x}) := -\sum_a \log f_a(\mathbf{x}_a)$
- ▶ Helmholtz free energy: $F_{Helmholtz} = -\log Z$
- ▶ Variational (or Gibbs) free energy:

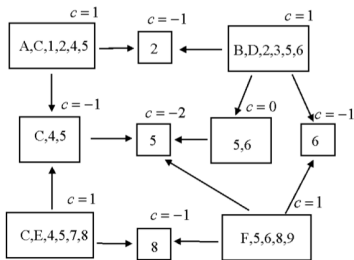
$$F(q) = \underbrace{\sum_{\mathbf{x}} q(\mathbf{x}) E(\mathbf{x})}_{U(q)} + \underbrace{\sum_{\mathbf{x}} q(\mathbf{x}) \log q(\mathbf{x})}_{-H(q)} \quad (2)$$

- ▶ $F(q) = F_{Helmholtz} + KL(q||p)$

Region Graph



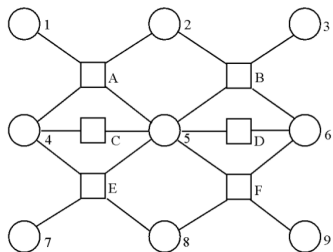
(a) factor graph



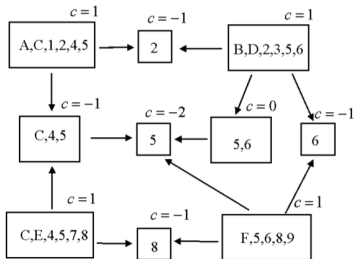
(b) region graph

- ▶ Recall a factor graph with vertices $I = \{i, a\}$
- ▶ A region graph is a labelled directed graph $\mathcal{G} = (V, E, L)$:
 - ▶ $v \in V$ is labelled by some subset $L(v) \subset I$
 - ▶ if $v_p \rightarrow v_c \in E$, then $L(v_c) \subset L(v_p)$
- ▶ A vertex $v \in V$ correspond to a region $R \subset I$

Region Graph



(c) factor graph



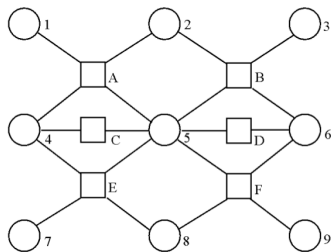
(d) region graph

- ▶ Region energy: $E_R(\mathbf{x}_R) := -\sum_{a \in f(R)} \log f_a(\mathbf{x}_a)$
- ▶ Region free energy:

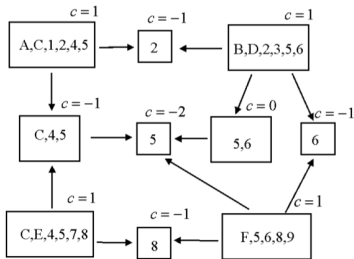
$$F_R(q_R) = \underbrace{\sum_{\mathbf{x}} q_R(\mathbf{x}_R) E_R(\mathbf{x}_R)}_{U_R(q_R)} + \underbrace{\sum_{\mathbf{x}_R} q_R(\mathbf{x}_R) \log q_R(\mathbf{x}_R)}_{-H_R(q_R)}$$

(3)

Region Graph



(e) factor graph



(f) region graph

- ▶ Define region count c_R (or c_v of corresponding vertex v):

$$\sum_{R \in \mathcal{R}} [a \in R] c_R = \sum_{R \in \mathcal{R}} [i \in R] c_R = 1$$
- ▶ $F(q) = \sum_{R \in \mathcal{R}} c_R F_R(q_R)$
- ▶ $U(q) = \sum_{R \in \mathcal{R}} c_R U_R(q_R), H(q) = \sum_{R \in \mathcal{R}} c_R H_R(q_R)$

Bethe Energy

- ▶ $\mathcal{R} = \mathcal{R}_L \cup \mathcal{R}_S$
 - ▶ $R \in \mathcal{R}_L$ only contains a factor node and its adjacent variable node
 - ▶ $R \in \mathcal{R}_S$ only contains one variable node
- ▶ $c_R = 1 - \sum_{S \in \mathcal{S}(R)} c_S$
 - ▶ $\mathcal{S}(R) = \{R' \in \mathcal{R} : L(R) \subset L(R')\}$
- ▶ $c_R = 1$, if $R \in \mathcal{R}_L$
- ▶ $c_R = 1 - d_i$, if $R \in \mathcal{R}_S$ contains variable i with degree d_i

Bethe Energy

- ▶ Bethe free energy: $F_{\text{Bethe}} = U_{\text{Bethe}} - H_{\text{Bethe}}$

$$\begin{aligned}U_{\text{Bethe}} &= - \sum_{a \in f(\mathcal{R})} \sum_{\mathbf{x}_a} q_a(\mathbf{x}_a) \log f_a(\mathbf{x}_a) \\H_{\text{Bethe}} &= - \sum_{a \in f(\mathcal{R})} \sum_{\mathbf{x}_a} q_a(\mathbf{x}_a) \log q_a(\mathbf{x}_a) \\&\quad + \sum_i (d_i - 1) \sum_{x_i} q_i(x_i) \log q_i(x_i)\end{aligned} \tag{4}$$

Bethe Approximation and Standard BP

Theorem

Let $\{M_{a \rightarrow i}(x_i), M_{i \rightarrow a}(x_i)\}$ be the BP messages and $\{q_a(\mathbf{x}_a), q_i(x_i)\}$ be the corresponding beliefs. Then the beliefs are fixed points of the BP algorithm iff. they are stationary points of the Bethe free energy F_{Bethe} .

- ▶ BP always has a fixed point
- ▶ Only one fixed point if there's no more than 1 cycle
- ▶ Exact approximation if no cycles in the factor graph:

$$p(\mathbf{x}) = \frac{\prod_i p_a(\mathbf{x}_a)}{\prod_i (p_i(x_i))^{d_i-1}} = q(\mathbf{x}) \quad (5)$$

Bethe Method: Inference

- ▶ assume the single and pairwise potentials satisfy

$$p(\mathbf{x}) = \frac{1}{Z_p} \prod_{(ij) \in E} \psi_{ij}(x_i, x_j) \prod_i \psi_i(x_i)$$

- ▶ define $\phi_{ij}(x_i, x_j) = \psi_{ij}(x_i, x_j)\psi_i(x_i)\psi_j(x_j)$
- ▶ also define $\phi_i(x_i) = \psi_i(x_i)$
- ▶ Rewrite the Bethe energy

$$F_{Bethe} = \sum_{(ij) \in E} \sum_{x_i, x_j} q_{ij}(x_i, x_j) \log \frac{q_{ij}(x_i, x_j)}{\phi_{ij}(x_i, x_j)} + \sum_i (1 - n_i) \sum_{x_i} q_i(x_i) \log \frac{q_i(x_i)}{\phi_i(x_i)} \quad (6)$$

Bethe Approximation

- ▶ Bethe approximation: minimize

$$F_{\text{Bethe}}(q) + \log Z_p \approx KL(q||p)$$

- ▶ Constraints of the approximation q :
 - ▶ observational constraint: $q(x_i) = \hat{\delta}_i(x_i)$
 - ▶ marginalization constraint: $\sum_{x_j} q_{ij}(x_i, x_j) = q_i(x_i)$
 - ▶ normalization constraint: $\sum_{x_i} q_i(x_i) = 1$
- ▶ The resulting Lagrangian

$$\mathcal{L} = F_{\text{Bethe}}(q) - \sum_i \sum_{j \in N(i)} \sum_{x_i} \lambda_{ji}(x_i) \left(\sum_{x_j} q_{ij}(x_i, x_j) - q_i(x_i) \right)$$

Bethe Approximation

Theorem

Subject to the constraints, the stationary points of F_{Bethe} is given by

$$q_{ij}(x_i, x_j) \propto \phi_{ij}(x_i, x_j) \exp(\lambda_{ji}(x_i) + \lambda_{ij}(x_j)) \quad (7)$$

$$q_i(x_i) \propto \phi_i(x_i) \exp\left(\frac{1}{d_i - 1} \sum_{j \in N(i)} \lambda_{ji}(x_i)\right) \quad (8)$$

where the Lagrange multipliers are fixed points of the following updates:

$$e^{\lambda_{ji}(x_j)} \leftarrow \prod_{k \in N(i) \setminus j} \sum_{x_k} \frac{\phi_{ik}(x_i, x_k)}{\phi_i(x_i)} e^{\lambda_{ik}(x_k)}, \quad \text{for hidden } i \quad (9)$$

$$e^{\lambda_{ji}(x_i)} \leftarrow \frac{\hat{\phi}_i(x_i)}{\sum_{x_j} \phi_{ij}(x_i, x_j) e^{\lambda_{ij}(x_j)}}, \quad \text{for observed } i \quad (10)$$

Bethe Approximation (Message Passing)

- ▶ Define messages $M_{i \rightarrow j}(x_j) = \sum_{x_i} \frac{\phi_{ij}(x_i, x_j)}{\phi_j(x_j)} e^{\lambda_{ji}(x_i)}$
- ▶ Rewrite (9)

$$e^{\lambda_{ji}(x_i)} \leftarrow \prod_{k \in N(i) \setminus j} M_{k \rightarrow i}(x_i), \quad \text{for hidden } i \quad (11)$$

- ▶ Recover BP updates

$$M_{i \rightarrow j}(x_j) \leftarrow \sum_{x_i} \frac{\phi_{ij}(x_i, x_j)}{\phi_j(x_j)} \prod_{k \in N(i) \setminus j} M_{k \rightarrow i}(x_i) \quad (12)$$

- ▶ Can also rewrite (10)

$$M_{i \rightarrow j}(x_j) \leftarrow \sum_{x_i} \psi_{ij}(x_i, x_j) \frac{\hat{\sigma}(x_i)}{M_{j \rightarrow i}(x_i)}, \quad \text{for observed } i \quad (13)$$

Bethe Method: Learning

- ▶ Maximum entropy: given (empirical) marginals \hat{p}

$$q^* = \arg \max_q H(q) \quad \text{s.t.} \quad q(\mathbf{x}_a) = \hat{p}(\mathbf{x}_a) \quad (14)$$

- ▶ Implementing constraints and the resulting Lagrangian

$$\mathcal{L} = H(q) - \sum_{a, \mathbf{x}_a} \lambda_a(\mathbf{x}_a) (\hat{p}(\mathbf{x}_a) - \sum_{\mathbf{x} \setminus a} q(\mathbf{x})) - \gamma (1 - \sum_{\mathbf{x}} q(\mathbf{x})) \quad (15)$$

- ▶ Zeroing derivatives of \mathcal{L} wrt. q and γ

$$q(\mathbf{x}) = \frac{1}{Z} e^{\sum_a \lambda_a(\mathbf{x}_a)} \quad (16)$$

Maximum Entropy

- ▶ Dual cost (convex)

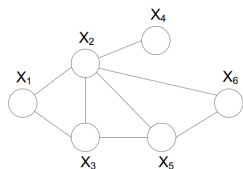
$$\mathcal{L}' = - \sum_{a, \mathbf{x}_a} \lambda_a(\mathbf{x}_a) \hat{p}(\mathbf{x}_a) + \log \sum_{\mathbf{x}} e^{\sum_a \lambda_a(\mathbf{x}_a)} \quad (17)$$

- ▶ Solved by coordinate-wise descent in λ_a

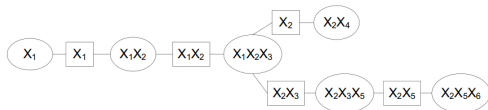
$$\lambda_a(\mathbf{x}_a) \leftarrow \lambda_a(\mathbf{x}_a) + \log \frac{\hat{p}(\mathbf{x}_a)}{q(\mathbf{x}_a)} \quad (18)$$

- ▶ Equivalent to $q(\mathbf{x}) \leftarrow q(\mathbf{x}) \frac{\hat{p}(\mathbf{x}_a)}{q(\mathbf{x}_a)}$
- ▶ Equivalent to maximum likelihood

Junction Trees



(g) graphical model



(h) junction tree

- ▶ Formed by maximal cliques C with separators S

$$q(\mathbf{x}) = \frac{\prod_{c \in C} q_c(\mathbf{x}_c)}{\prod_{s \in S} q_s(\mathbf{x}_s)} \quad (19)$$

- ▶ For any cluster a , there exist $c \in C$ s.t. $a \subset c$
- ▶ $q_{c_1}(\mathbf{x}_s) = q_{c_2}(\mathbf{x}_s)$ if c_1, c_2 are neighbouring cliques separated by s

Junction Trees

- ▶ Learning by maximum entropy

$$\arg \max_{\{q_c, q_s\}} \sum_c H(q_c) - \sum_s H(q_s) \quad (20)$$

subject to $q_c(\mathbf{x}_a) = \hat{p}_a(\mathbf{x}_a)$, $q_c(\mathbf{x}_s) = q_s(\mathbf{x}_s)$, $\forall a, s \subset c$

- ▶ The resulting Lagrangian (def. $a \subset c_a$)

$$\begin{aligned} \mathcal{L} = & \sum_c H(q_c) - \sum_s H(q_s) - \sum_{v \in \text{SUC}} \gamma_v \left(\sum_{\mathbf{x}_v} q_v(\mathbf{x}_v) - 1 \right) \\ & - \sum_{c, s, \mathbf{x}_s} \lambda_{cs}(\mathbf{x}_s) (q_s(\mathbf{x}_s) - \sum_{\mathbf{x}_c \setminus s} q_c(\mathbf{x}_c)) \\ & - \sum_{a, \mathbf{x}_a} \lambda_a(\mathbf{x}_a) (\hat{p}_a(\mathbf{x}_a) - \sum_{\mathbf{x}_{c_a} \setminus a} q_{c_a}(\mathbf{x}_{c_a})) \end{aligned} \quad (21)$$

Junction Trees

Theorem

Define $A_c := \{a | c_a = c\}$. Then solving the Lagrangian returns marginal distributions

$$q_c(\mathbf{x}_c) \propto e^{\sum_s \lambda_{cs}(\mathbf{x}_s) + \sum_{a \in A_c} \lambda_a(\mathbf{x}_a)} \quad (22)$$

$$q_s(\mathbf{x}_s) \propto e^{\sum_c \lambda_{cs}(\mathbf{x}_s)} \quad (23)$$

while λ_a and λ_{cs} are the fixed points of the following updates

$$\lambda_a(\mathbf{x}_a) \leftarrow \lambda_a(\mathbf{x}_a) + \log \frac{\hat{p}_a(\mathbf{x}_a)}{q_{c_a}(\mathbf{x}_{c_a})} \quad (24)$$

$$e^{\lambda_{c's}} \leftarrow \alpha \sum_{\mathbf{x}_{c \setminus s}} e^{\sum_{s' \neq s} \lambda_{cs'}(\mathbf{x}_{s'}) + \sum_a \lambda_{ca}(\mathbf{x}_a)} \quad (25)$$

where c' , c are separated by s , and s' are other separators neighbouring c .

Junction Trees (Message Passing)

- ▶ Define messages and potentials (factors)

$$M_{C \rightarrow S}(x_S) := e^{\lambda_{CS}(x_S)}, \quad f_C(\mathbf{x}_C) := e^{\sum_a \lambda_{Ca}(\mathbf{x}_a)}$$

- ▶ (25) is equivalent to

$$M_{C' \rightarrow S}(x_S) \leftarrow \propto \sum_{\mathbf{x}_{C \setminus S}} f_C(\mathbf{x}_C) \prod_{S' \neq S} M_{C \rightarrow S'}(x_{S'}) \quad (26)$$

- ▶ Rewrite the marginals (22) and (23)

$$q_C(\mathbf{x}_C) \propto f_C(\mathbf{x}_C) \prod_S M_{C \rightarrow S}(x_S), \quad q_S(\mathbf{x}_S) \propto \prod_C M_{C \rightarrow S}(x_S)$$

- ▶ ... or by Hugin propagation

$$q_{C'}(\mathbf{x}_{C'}) \leftarrow q_{C'}(\mathbf{x}_{C'}) \frac{q_C(\mathbf{x}_S)}{q_S(\mathbf{x}_S)}, \quad q_S(\mathbf{x}_S) \leftarrow q_C(\mathbf{x}_S)$$

EP energy

- ▶ EP approximation

$$p(\mathbf{x}|D) = p(\mathbf{x}) \prod_i^n t_i(\mathbf{x}) \approx p(\mathbf{x}) \prod_i \tilde{t}_i(\mathbf{x}) := q(\mathbf{x}) \quad (27)$$

- ▶ $\tilde{t}_i(\mathbf{x}) = e^{\sum_j f_j(\mathbf{x})\tau_j}$
- ▶ Minimizing (local) KL-divergence $KL(\hat{p}_i||q)$ where $\hat{p}_i := q \setminus t_i$
- ▶ ... by matching the expectations $E_{\hat{p}_i}[f_j]$ and $E_q[f_j]$
- ▶ May want q and \hat{p}_i to be normalised

EP energy

- ▶ The EP primal energy function (satisfying moment matching and normalization constraints)

$$\min_{\hat{p}_i} \max_q \sum_i^n KL(\hat{p}_i || t_i p) - (n-1)KL(q || p) \quad (28)$$

- ▶ (Dual) energy function

$$\begin{aligned} \min_{\nu} \max_{\lambda} (n-1) \log \int_{\mathbf{x}} p(\mathbf{x}) e^{\sum_j f_j(\mathbf{x}) \nu_j} d\mathbf{x} \\ - \sum_i^n \log \int_{\mathbf{x}} t_i(\mathbf{x}) p(\mathbf{x}) e^{\sum_j f_j(\mathbf{x}) \lambda_{ij}} d\mathbf{x} \end{aligned} \quad (29)$$

$$\text{s.t. } (n-1)\nu_j = \sum_i \lambda_{ij}$$

Equivalence between BP and Bethe Energies

- ▶ BP is a special case of EP that f_j are delta functions
- ▶ Recall the Bethe energy

$$F_{\text{Bethe}} = \underbrace{\sum_{(ij) \in E} \sum_{x_i, x_j} q_{ij}(x_i, x_j) \log \frac{q_{ij}(x_i, x_j)}{\phi_{ij}(x_i, x_j)}}_{\textcircled{1}} - \underbrace{\sum_i (n_i - 1) \sum_{x_i} q_i(x_i) \log \frac{q_i(x_i)}{\phi_i(x_i)}}_{\textcircled{2}}$$

- ▶ ... minimizing F_{Bethe} is by updating

$$q_{ij}(x_i, x_j) \propto \phi_{ij}(x_i, x_j) \exp(\lambda_{ji}(x_i) + \lambda_{ij}(x_j))$$

Equivalence between BP and Bethe Energies

- ▶ Another representation of the KL-divergence

$$KL(P||Q) = \max_{\nu} E_P[\nu(x)] - \log E_Q[e^{\nu(x)}] \quad (30)$$

- ▶ Apply to the Bethe energy

$$\begin{aligned} \textcircled{1} &= \max_{\lambda} \sum_{x_i} q_i(x_i) \lambda_{ji}(x_i) + \sum_{x_j} q_j(x_j) \lambda_{ij}(x_j) \\ &\quad - \log \sum_{x_i, x_j} \phi_{ij}(x_i, x_j) e^{\lambda_{ji}(x_i) + \lambda_{ij}(x_j)} \end{aligned} \quad (31)$$

$$\textcircled{2} = \min_{\nu} - \sum_i (n_i - 1) \sum_{x_i} q_i(x_i) \nu(x_i) + \log \sum_{x_i} \phi_i(x_i) e^{\nu(x_i)} \quad (32)$$

Equivalence between BP and Bethe Energies

- ▶ Substitute (31), (32) into $\min_q F_{Bethe}$ and zeroing the gradient wrt. ν and λ :

$$q_i(x_i) = \frac{\phi_i(x_i)e^{\nu(x_i)}}{Z_1} = \frac{\sum_{x_j} \phi_{ij}(x_i, x_j)e^{\lambda_{ji}(x_i)+\lambda_{ij}(x_j)}}{Z_2} \quad (33)$$

- ▶ Add constraint $(n_i - 1)\nu(x_i) = \sum_j \lambda_{ji}(x_i)$ to delete $q_i(x_i)$, then have the transformed objective

$$\min_{\nu} \max_{\lambda} \sum_i (n_i - 1) \log \sum_i \phi_i(x_i)e^{\nu(x_i)} - \sum_{(ij) \in E} \log \sum_{x_i, x_j} \phi_{ij}(x_i, x_j)e^{\lambda_{ji}(x_i)+\lambda_{ij}(x_j)} \quad (34)$$

Bethe Approximation, BP and EP

- ▶ Recall the coincidence of BP fixed points and Bethe energy stationary points
- ▶ EP extends BP
- ▶ EP fixed points = stationary points of some free energy function

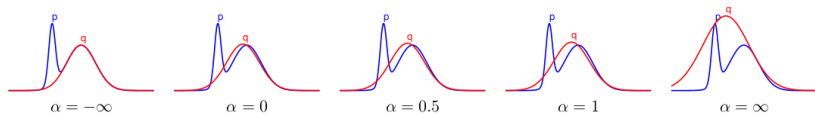
Power EP and α -Divergences

- ▶ Power EP: minimizing (local) KL-divergence $KL(q(\frac{t_i}{\hat{t}_i})^\alpha || q)$
- ▶ Equivalent to minimize the α -divergence

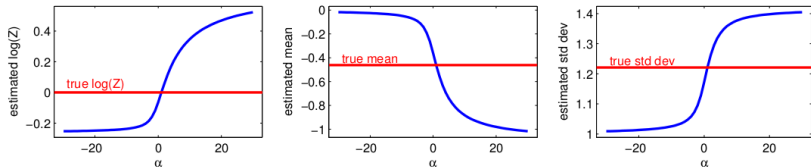
$$D_\alpha(\hat{p}_i || q) := \frac{\int_{\mathbf{x}} \alpha \hat{p}_i(\mathbf{x}) + (1 - \alpha)q(\mathbf{x}) - \hat{p}_i(\mathbf{x})^\alpha q(\mathbf{x})^{(1-\alpha)} d\mathbf{x}}{\alpha(1 - \alpha)} \quad (35)$$

- ▶ $\lim_{\alpha \rightarrow 0} D_\alpha(p || q) = KL(q || p)$
- ▶ $\lim_{\alpha \rightarrow 1} D_\alpha(p || q) = KL(p || q)$

Power EP and α -Divergences



(i) The Gaussian q which minimizes α -divergence to p (a mixture of two Gaussians)



(j) The mass, mean, and standard deviation of the Gaussian q which minimizes α -divergence to p