Compressed Sensing and Related Learning Problems

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Overview

- Background
- Compressed Sensing
 - Norms Indicating Sparsity
 - Restricted Isometry Property (RIP)
 - Recovery Algorithms
 - Applications
- Learning Methods
 - Probabilistic Methods
 - Dictionary Learning
- Conclusion

Please refer to my thesis for details.

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Background

- Signal processing everywhere.
 - Entertainment: music, videos, images...
 - Engineering: telecommunication, medical use...
 - Recognition: speech, face, moving object...
- Limitation of the Nyquist-Shannon Sampling Theorem
- Era of the big data.
 - Daily life accompanied with data.
 - Knowledge discovery from data.
- Any fast algorithms?

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Why use I_1 -Norm?



• Recovery of the signal $f \in \mathbb{R}^n$ from $\mathbf{y} \in \mathbb{R}^m$:

$$f^* = \arg\min_{f} ||f||_p \ s.t. \ \mathbf{y} = \Phi f. \tag{1}$$

Restricted Isometry Property



Definition (Restricted Isometry Property [CT05])

The sensing matrix Φ is said to obey the restricted isometry property of order S if $\exists \delta_S$ s.t. \forall k-sparse f such that $k \leq S$, and f's support $T \subset \{1, 2, ..., n\}(|T| = k)$,

$$(1 - \delta_{\mathcal{S}})||f||_{2}^{2} \le ||\Phi_{\mathcal{T}}f||_{2}^{2} \le (1 + \delta_{\mathcal{S}})||f||_{2}^{2}.$$
 (2)

Sampling Constraints

Theorem (Equivalence of problem (P_0) and (P_1))

Suppose $S \ge 1$ and $\delta_{2S} < 1$, the solutions of (P_0) and (P_1) coincides if that solution f has its support T satisfying $|T| \le S$.

Theorem (Noiseless incoherent sampling [CT06])

If f is k-sparse, then for any $\beta > 0$, with probability at least $1-5/n-e^{-\beta}$ the signal can be perfectly recovered if $m \gtrsim O(k \log n)$

• Random sensing matrix works better.

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Simulations: solving BP by LP



Noisy Recovery



- In practise $\mathbf{y} = \mathbf{\Phi} \mathbf{f} + \sigma \mathbf{z}$.
- LASSO: *l*₂-minimization with *l*₁-penalty.

$$f^* = \arg\min_{f} \frac{1}{2} ||\Phi f - \mathbf{y}||_2^2 + \lambda \sigma_m ||f||_1$$
(3)

• Similar (weak) RIP guarantees the recovery.

Single-Pixel Camera



(a) ideal image



(b) 400 largest wavelets



(c) 675 largest wavelets



(d) image on DMD



(e) 1600 measurements



(f) 2700 measurements

(a)

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Figure: Compressed sensing v.s. wavelet decomposition [TLW⁺06].

Applications

CS-MRI



Figure: Applying CS techniques to MRI [LDSP08].

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$$f^* = \arg\max_{f} (\log P(\mathbf{y}|f; \Phi) + \log P(f)). \tag{4}$$

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•
$$\mathbf{y} - \Phi f = \mathbf{z} \sim \mathcal{N}(\mathbf{0}, \sigma^2)$$

• Prior $P(f) = \frac{1}{Z} e^{-\lambda_p ||f||_p}$
 $\Rightarrow f = \arg\min_f ||\mathbf{y} - \Phi f||_2^2 + \lambda ||f||_p$
 $\Rightarrow f = \arg\min_f ||f||_p \ s.t. \ ||\mathbf{y} - \Phi f||_2 \le \epsilon$
(5)

- p = 1: standard LASSO
- $\epsilon \rightarrow 0$: perfect recovery.

Dictionary Learning

• Finding the dictionary minimizing the error of representation:

$$\Psi^* = \arg\min_{\Psi} ||\mathbf{Y} - \Phi \Psi \mathbf{X}||_F^2 \tag{6}$$

- X is supposed to be sparse.
- K-SVD [AEB06].
- Expectation-Maximization.

Maximum Likelihood

• Signal can be represented by some fixed codes from an over-complete dictionary:

$$f = \Psi \mathbf{x} + \mathbf{v}, \ \mathbf{v} \sim \mathcal{N}(0, \sigma^2)$$
 (7)

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• Best dictionary gives sparse representations $||\mathbf{x}||_1 \leq \epsilon$:

$$\Psi^* = \arg \max_{\Psi} \sum_{f} \int_{||\mathbf{x}||_1 \le \epsilon} e^{-\frac{1}{2\sigma'^2} ||f - \Psi \mathbf{x}||_2^2 - \lambda_1 ||\mathbf{x}||_1}$$
(8)

• Trick: fast online methods.

Conclusion

• Revolutionary sensing theories without Nyquist rate constraints.

- Benefited from data sparsity.
- The RIP helps yield perfect recovery with high probability.
- Random sensing matrix works better.
- Learning algorithms benefits CS methods.

Future Research

• Can the algorithms keep high performance when *n* grows?

- Can $P(\Phi)$ be learned?
- Can we loose the restriction of (weak) RIP?
- Any other learning approaches?

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